



Active Safety and Cooperative Systems in the Road Infrastructure of the Future

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Road Safety Event Athens 1st of March 2011



Traffic Safety: Putting the legos in place

- Traffic safety risk emanates from the cooperation of three main factors: driver-vehicle-traffic environment.
- Measures in order to support/improve any of these factors, may have negative side-effects to the others.
- According to the risk homeostasis theory (Wilde 2001), the enhancement of safety level of a vehicle leads sometimes drivers to change their driving profile, undertaking more risky maneuvers, in order to keep their conceived level of risk constant.
- Thus, optimal measures to improve to all three contributors or build upon the strengths and interactions between each combined environment.
- Alternatives for the safety hazards, can be based upon Autonomous (e.g. only Infrastructure or in-vehicle based) or Co-operative solutions (e.g. V2V, I2V, or/and In-Vehicle ones).







The two pillars of Road Safety and Infrastructure:

I. Forgiving Roads

A forgiving road is defined as a road that is designed and built in such a way as to interfere with or block the development of driving errors and to avoid or mitigate negative consequences of driving errors, allowing the driver to regain control and either stop or return to the travel lane without injury or damage.







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II. Self-explanatory Roads

Self-explanatory road is defined as one that is designed and constructed to evoke correct expectations from road users and elicit proper driving behaviour, thereby reducing the probability of driver errors and enhancing driving comfort.





High-Speed Through Roads (Pictures courtesy of CROW, BASt)





We are living in a cooperative world...





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This is true when we are on the road too...



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Cooperative Systems (indicative)

- Speed adaptation (V2I and I2Vcommunication)
- Reversible lanes due to traffic flow (V2I and I2V)
- Local danger / hazard warning (V2V)
- Post crash warning (V2V)
- Cooperative intersection collision warning (V2V and V2I)





Cooperative Systems - Potential Impacts

- According to CODIA Final Report, Cooperative systems showed high potential to contribute to improved traffic safety (Kulmala, 2008).
- Dynamic speed adaptation showed most potential (-7%) to decrease fatalities.
- The cooperative intersection collision warning and local danger warning comes next (-4%).
- The potential of injury prevention is higher for cooperative inter-section collision (-7%) followed by dynamic speed adaptation (-5%).
- The reversible lane system decreases the fatalities and injuries on the sections equipped. However, a very small part of the motorway and urban network are suitable for the system.
- The SAFESPOT impact analysis study showed considerable safety effects resulting in 7.1 % less fatalities for the V2V case, and 8.9 % for the V2I case, assuming a 100 % penetration rate of cooperative systems into the vehicle fleet (Schindhelm, 2010).





Some ideas...

1. Virtual Rumble Strip

• Vehicle lateral and rear monitoring system (LRM)



Lane Departure Warning / Lane keeping Systems (LDWS)



• Collision Avoidance Systems (CAS), for the lateral area, including lane change support systems.











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2. VSL Application



Measured Accident cost reduction due to VSL application (Gunnar Lind, "Cost-Benefit Analysis of ITS", Movea Trafikkonsult AB, April 2009.)



VSL application





3. VMS Application



Time benefits due to early warning on road closure or accident ahead through VMS (Gunnar Lind, "Cost-Benefit Analysis of ITS", Movea Trafikkonsult AB, April 2009.)





VMS application Road Safety Event Athens , 1st of March 2011



IN-SAFETY infrastructure node equipment



In vehicle personalized priority information...





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4. Smart Strip Concept



Smart Strip miniaturised multi-sensorial platform at a highway or rural environment.



Smart Strip miniaturised multisensorial platform at an intersection/merging application.





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Smart Strip "Highway" scenario



Smart Strip Type-applications:

Magnetic sensors for traffic management

Magnetic sensors dedicated to various applications that provide relevant information such as:

- Basic vehicle detection
- Raw classification of vehicle
- Local speed estimation; acceleration; lateral position in lane
- Lane change detection

 By sensing data in spaced strips (sparse or dense) much richer information can be obtained with sensor data fusion (e.g. object tracking).

Passive follower sensors embedded in road

Such a system will require a larger frequency spectrum to be operational than the standard RFID bands (e.g. 125 kHz & 13.56 MHz).





TECHNOLOGY

Nanosensors for road and environmental sensing



Smoke detection by optically active molecules



Photos of the two humidity sensors fabricated on polycarbonate membranes with adhesive paper shadow masks.

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PictosNOTinViennaConvention.pdf

5. Standardization of Electronic Info

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Dissemination Level (PU/RP/CO)

Contract No TREN-04-FP6TR-S07.38213/506716





RESEARCH AND

Based upon an extension of standard signs standardization (Vienna Convention)

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A-4a Carriageway narrows					
A-4b Carriageway narrows					
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6. Modelling

Micro and macro modelling:







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Steps to be taken...

- Initial model adapted for Traffic Safety impact analysis.
- ADAS equipped vehicles of different types (car, truck, PTW) modelled.
- Run without ADAS.
- Run with "ideal" ADAS behavior.
- Run with real ADAS behavior.
- Run with multiple ADAS.

>All for different penetration rates and road types.



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TECHNOLOGY

Training 7.

Operators' Training MMT:



Wrong Way Driver Warning Syst



info functionality time frame, support type benefits 0oS limitations standards guidance examples prospects

Embedded Sensors, Videos, and Flashing Lights

When electromagnetic sensors embedded in the ramp pavement detect a wrong-way vehicle, the system performs three primary functions. First, two signs mounted on both sides of the northbound exit ramp begin flashing an alternating red-yellow "Wrong Way" message for several minutes. At the same time, a closed-circuit video camera and time-lapse VCR record the incident to help traffic engineers determine the cause of the wrong-way incident and develop measures to prevent future wrong-way crashes. Electromagnetic sensors embedded in the pavement (the three dark squares) detect vehicles moving in the wrong direction (above). When the sensors determine a vehicle is travelling the wrong way, the message sign illuminates a red "Wrong Way" message (above).



This system will use a Traficon Video Detection system, which consists of a camera installed on a signal pole. When the video detector is activated, a signal is transmitted to the message sign, which





INTRODUCTION THE PROBLEM SELF EXPLAINING & FORGIVING ROADS TELEMATICS » ITS » ITS for private vehicles » ITS for public transport » ITS for commercial vehicles » ITS for infrastructure Traffic Information Systems(TIS) » Traffic Management Systems(TMS) Wrong way driver warning system Video surveilance Floating Car Data (FCD) Ramp metering » Incident Management Systems **Tunnel Management** Electronic Tolling and Road Use Charging Enforcement Systems » ITS for vehicle control » Cooperative ITS

» STANDARDS & BODIES

www.insafety-eu.org

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Finally...

Towards a real self-explanatory and comfortable driving environment....





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...and a forgiving one too!!!



